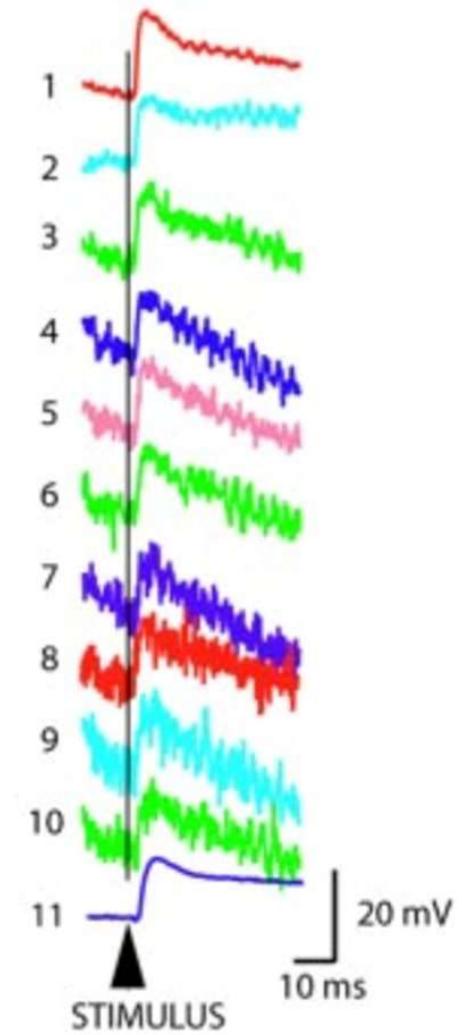
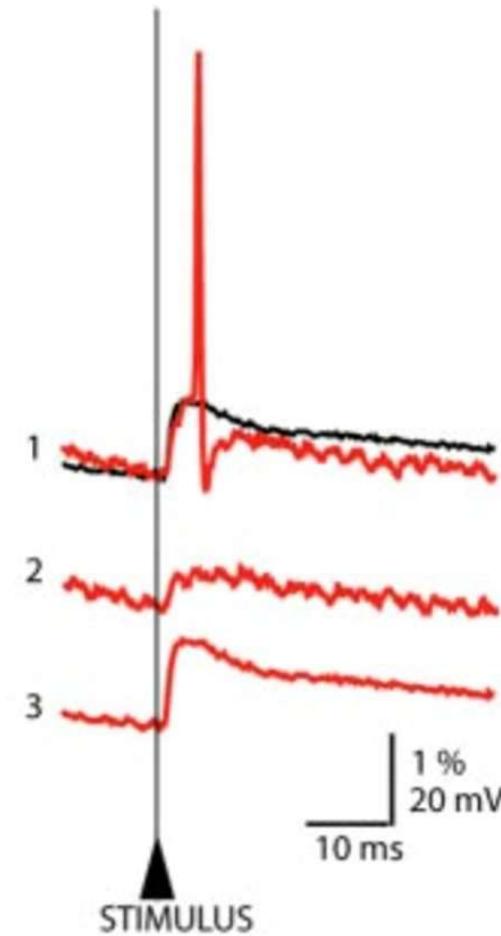
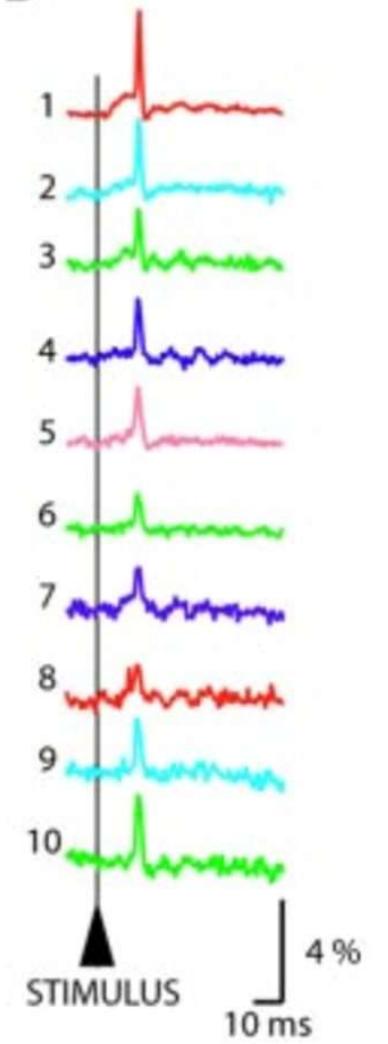
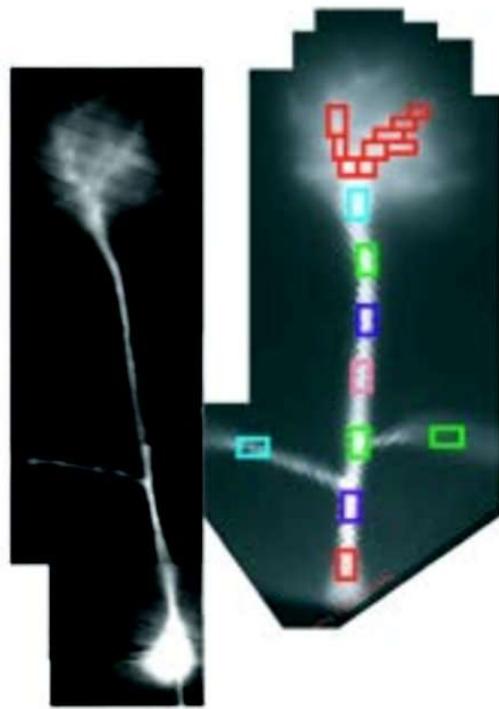


# Statistical inference in nonlinear stochastic neurones

Quentin Huys  
Misha Ahrens  
Liam Paninski

# How can we use rich new data to build models efficiently?

Quentin Huys  
Misha Ahrens  
Liam Paninski



simultaneous multisite recordings of transmembrane voltage  
noisy

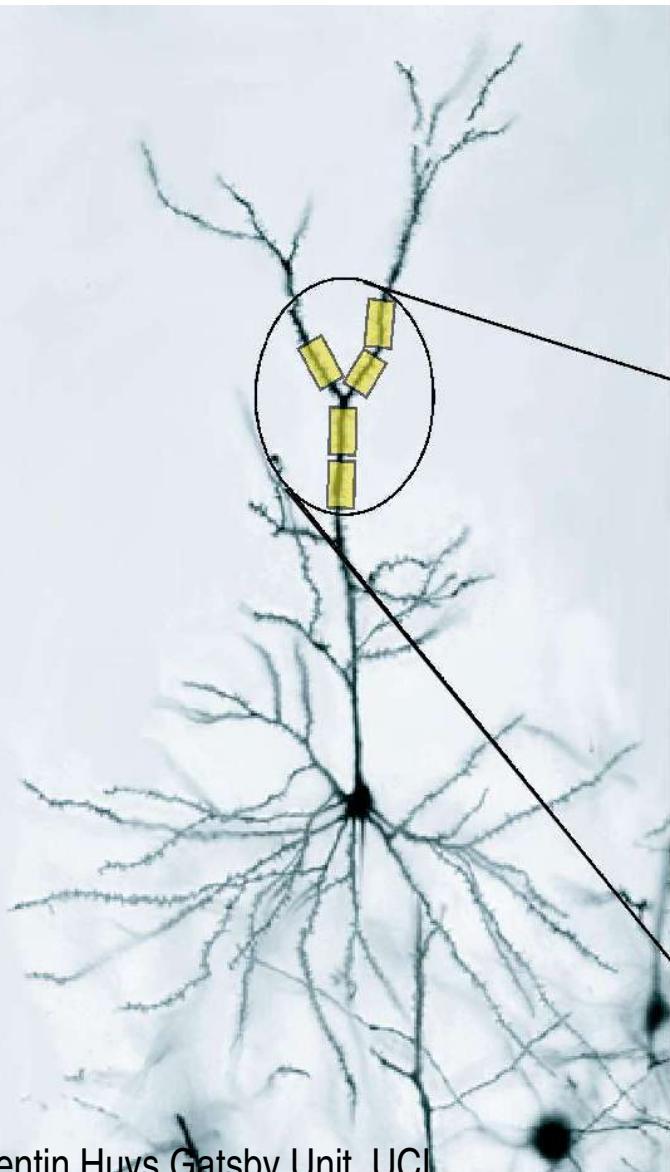
Djurisic et al. 2004

# IO function    $O=f(I)$

- $f$ : cable equation – compartmental model
  - nonlinear dynamics
- Output?
  - rate, individual spikes, bursts, spike patterns?
  - stochastic formulation gives metric
- Input?
- Noise?

# A stochastic neurone

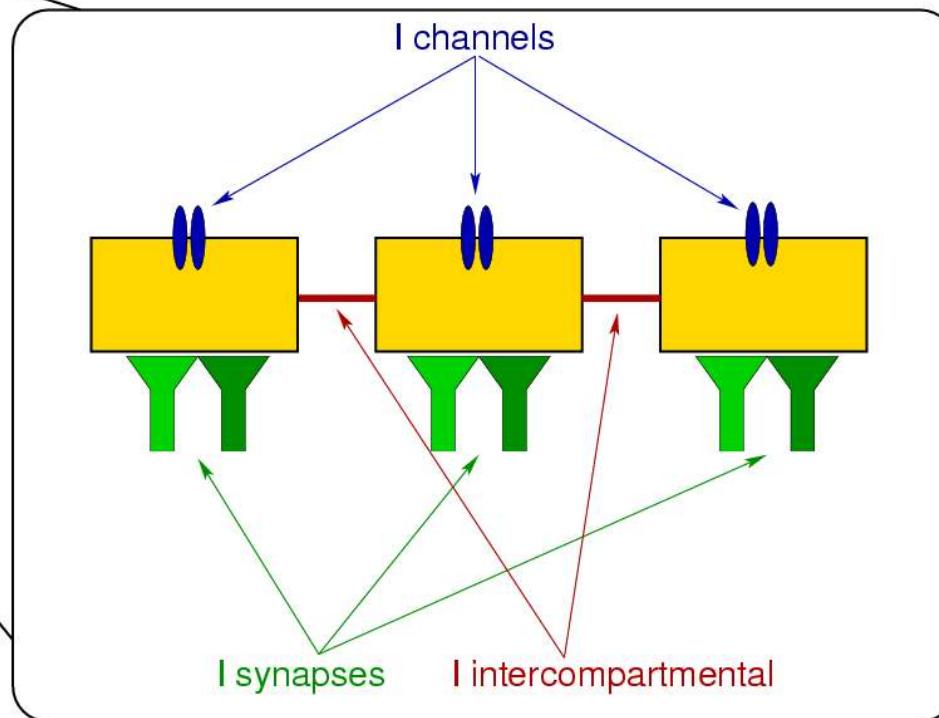
$$C_x \frac{dV_x(t)}{dt} = I_{\text{ch}} + I_{\text{int}} + I_{\text{syn}} + \sigma_x dN_{x,t}$$



$$I_{\text{channels}} = \bar{g}_c g_c(t)(E_c - V(t))$$

$$I_{\text{synaptic}} = \sum_{\tau} w_{\tau} u_{\tau}^s(t)(E_s - V(t))$$

$$I_{\text{intercompartmental}} = f_{x,y}(V_y(t) - V_x(t))$$



# Outline

- Assume known kinetics and noiseless observations
- Relax
  - noisy observations
    - model-based smoothing
    - parameter inference
  - unknown kinetics

# Known kinetics

$$C_x \frac{dV_x(t)}{dt} = I_{\text{ch}} + I_{\text{int}} + I_{\text{syn}} + \sigma_x dN_{x,t}$$

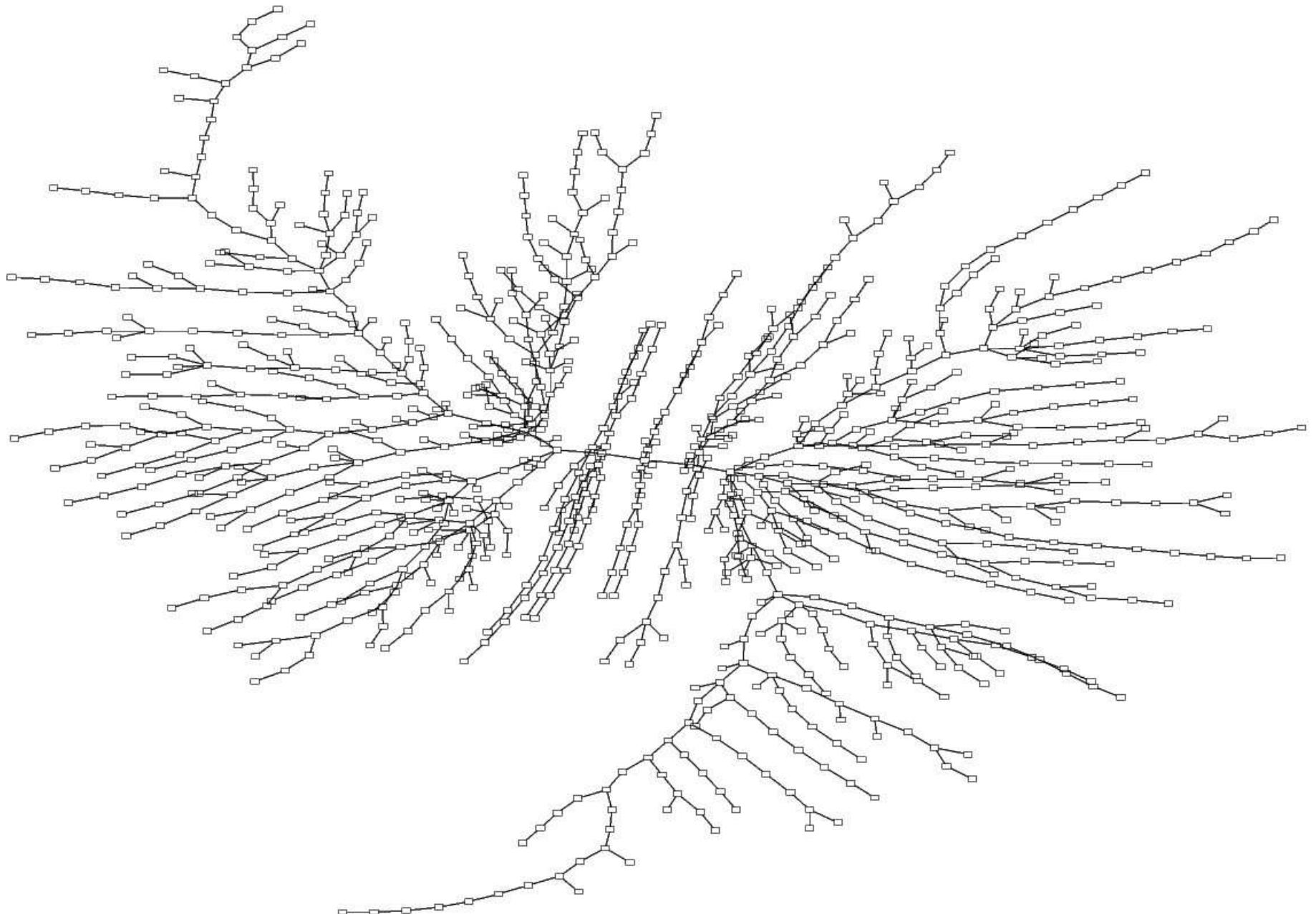
$$I_{\text{channels}} = \bar{g}_c g_c(t)(E_c - V(t))$$

$$\begin{aligned}\frac{dx}{dt} &= (1-x)\alpha(V(t)) - x_t\beta(V(t)) \\ x_{t+1} &= x_t + dt [(1-x_t)\alpha(V_t) - x_t\beta(V_t)]\end{aligned}$$

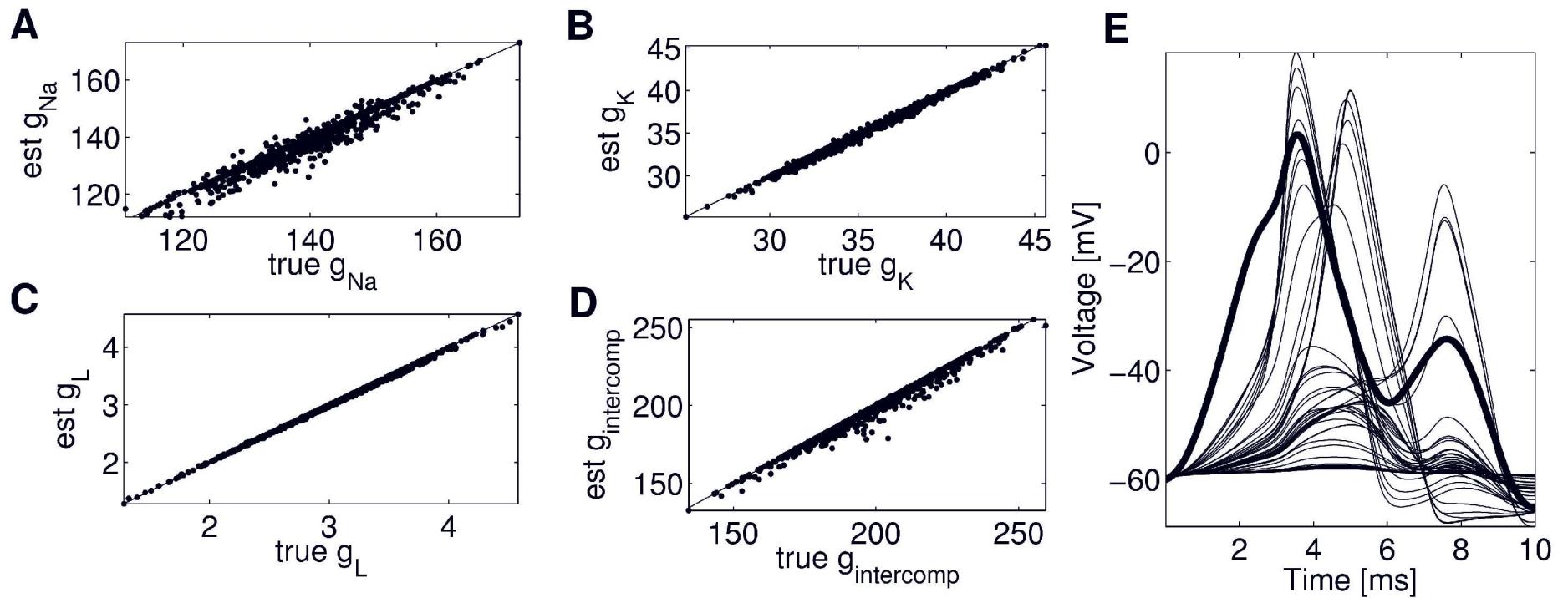
$$I_{\text{synaptic}} = \sum_{\tau} \bar{w}_{\tau} u_{\tau}^s(t)(E_s - V(t))$$

$$I_{\text{intercompartmental}} = \bar{f}_{x,y}(V_y(t) - V_x(t))$$

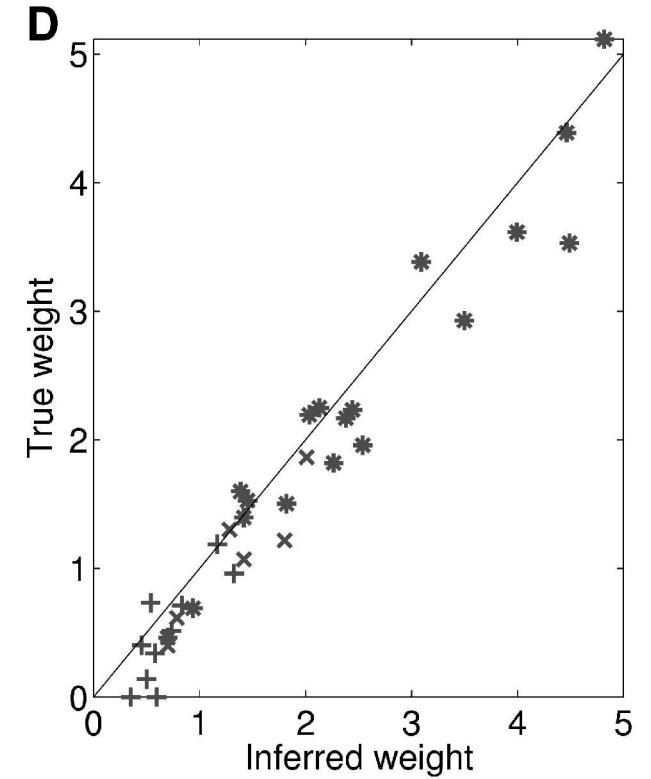
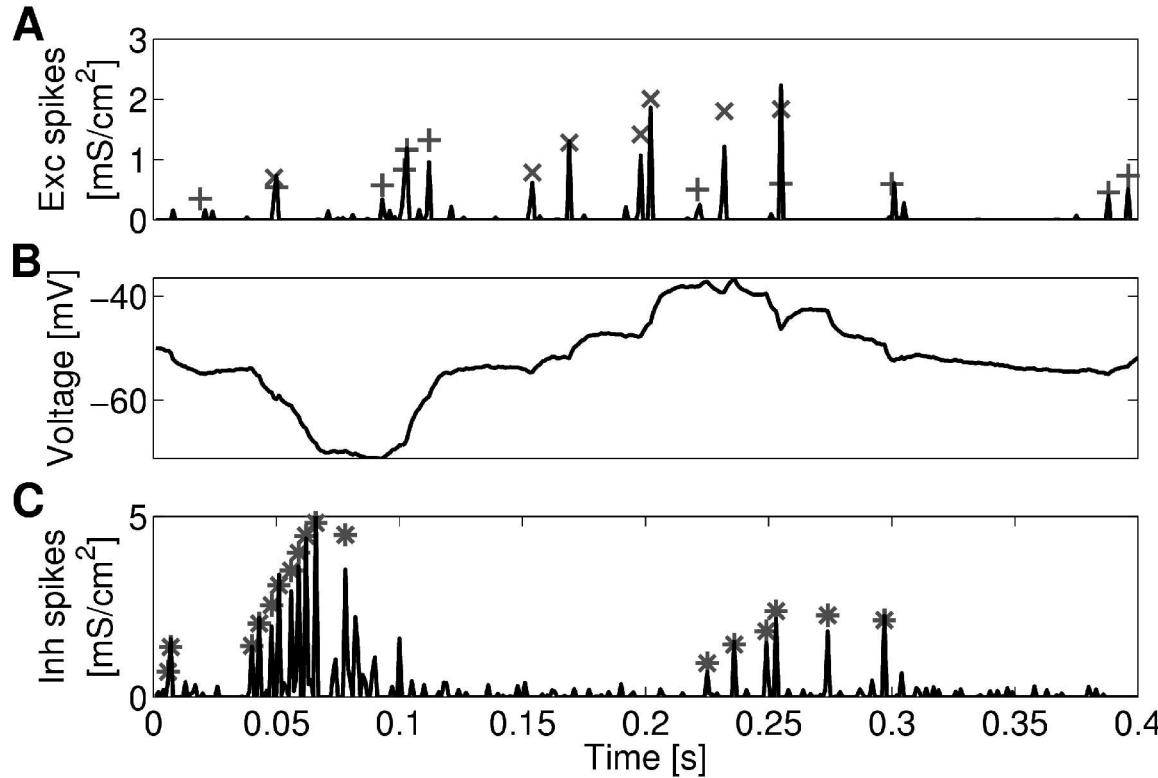
# A big cell – 1000 compartments



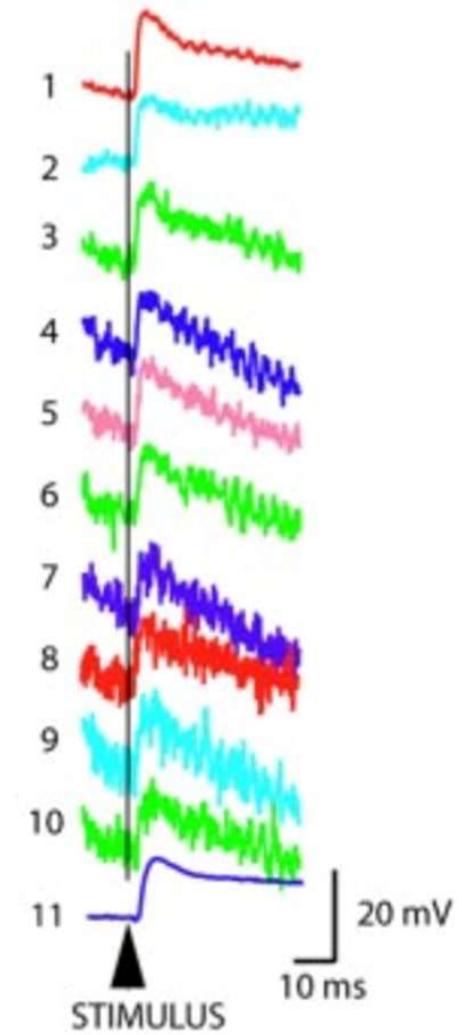
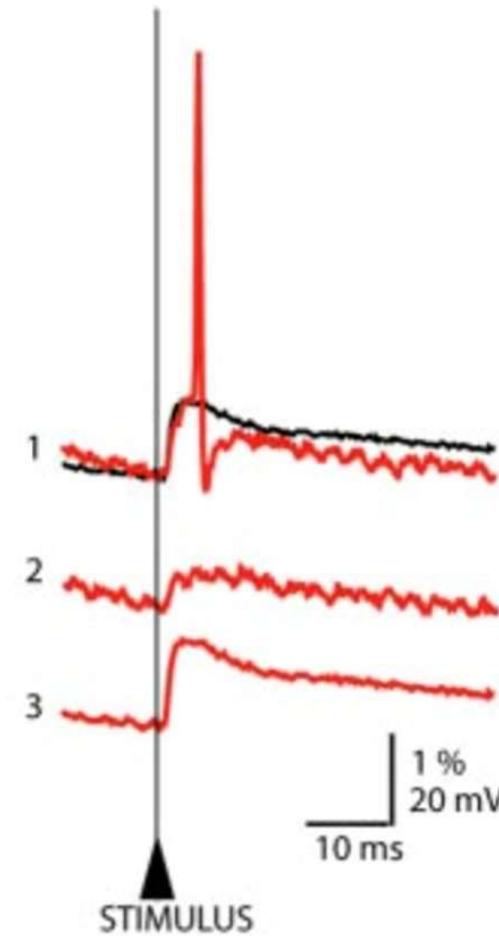
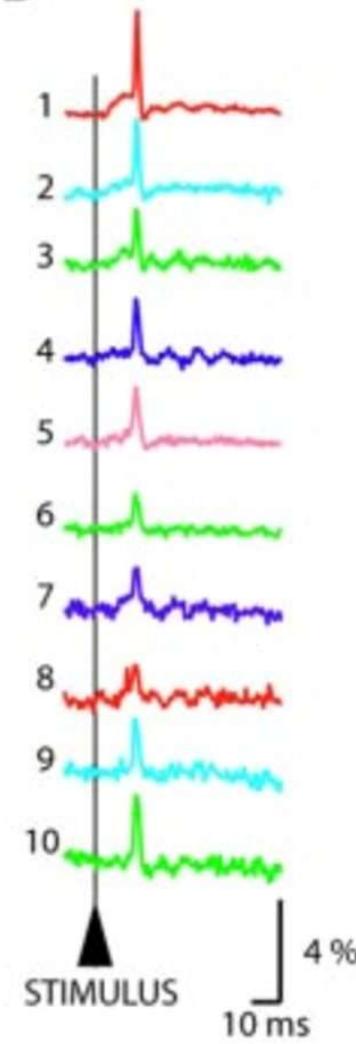
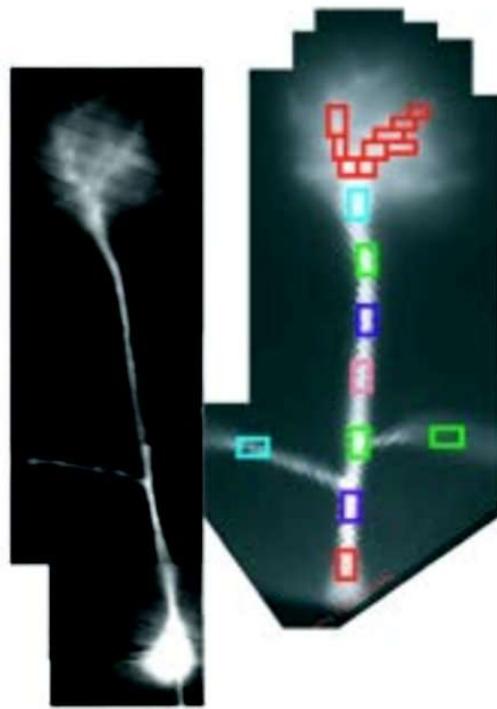
# Channel density distribution



# Synaptic input



$$I_{\text{synaptic}} = \sum_{\tau} \textcolor{red}{w}_{\tau} u_{\tau}^s(t)(E_s - V(t))$$



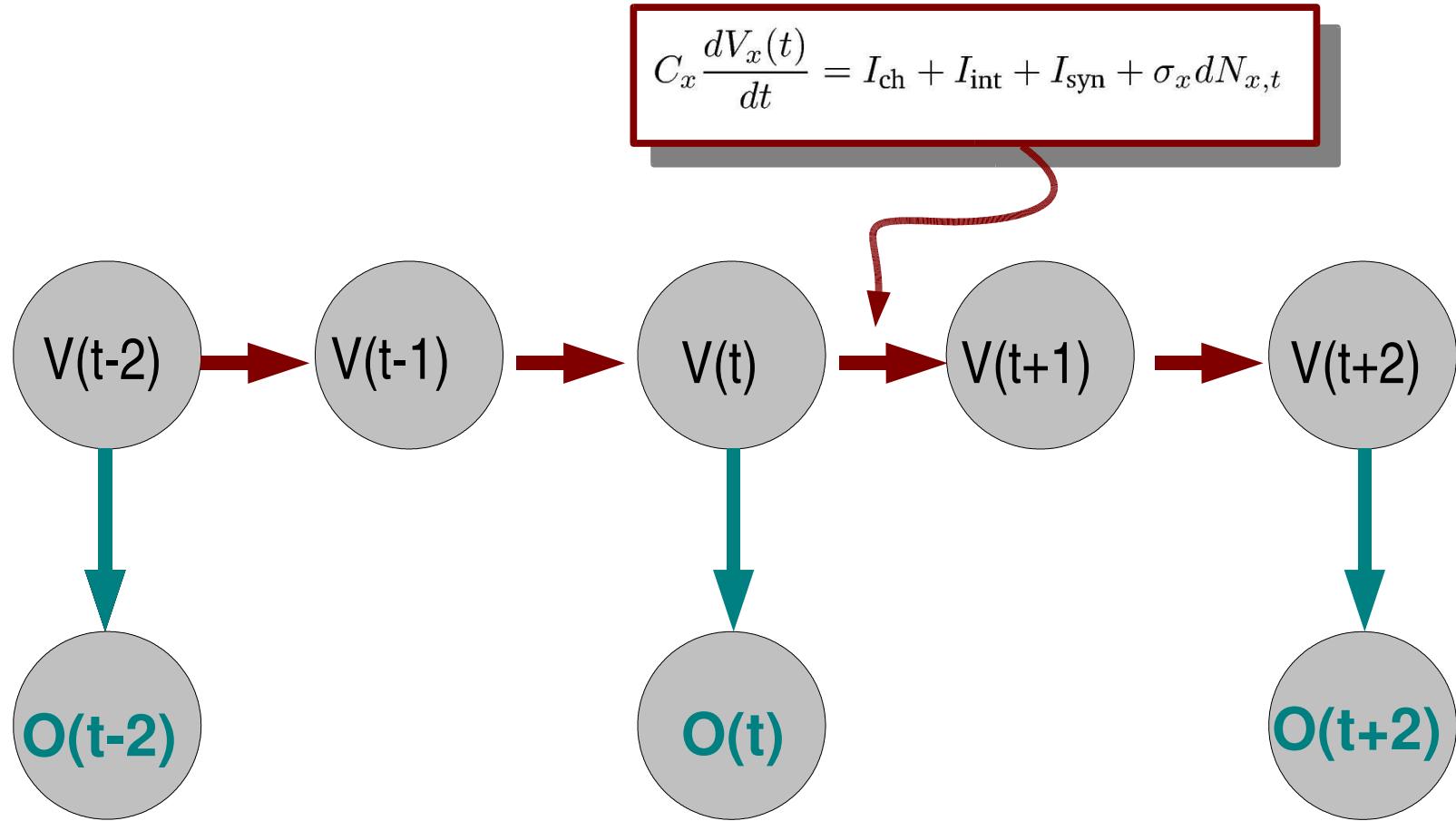
simultaneous multisite recordings of transmembrane voltage  
noisy

Djurisic et al. 2004

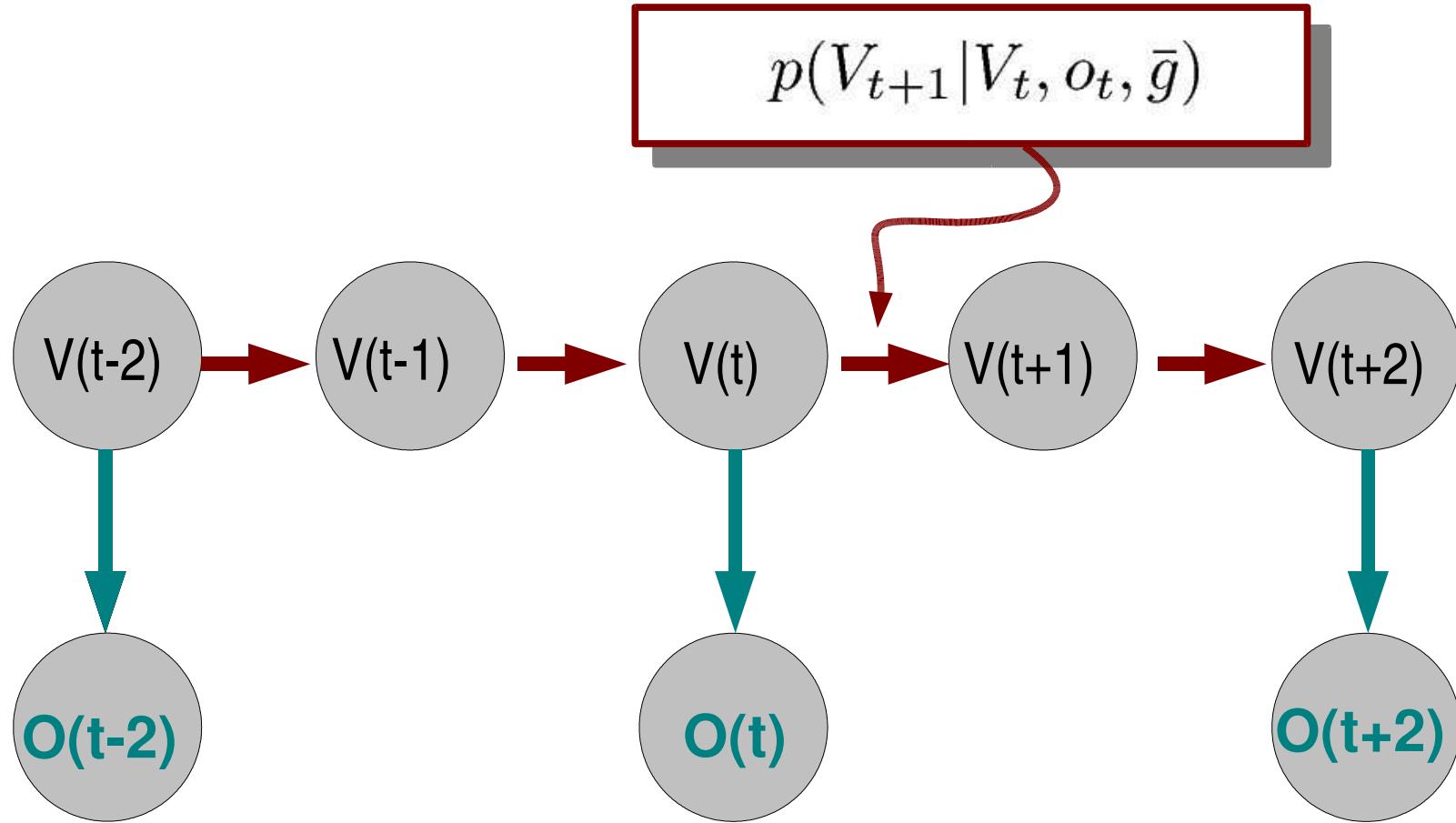
# Outline

- Assume known kinetics and noiseless observations
- Relax
  - noisy observations
    - model-based smoothing (E)
    - parameter inference (M)
  - unknown kinetics

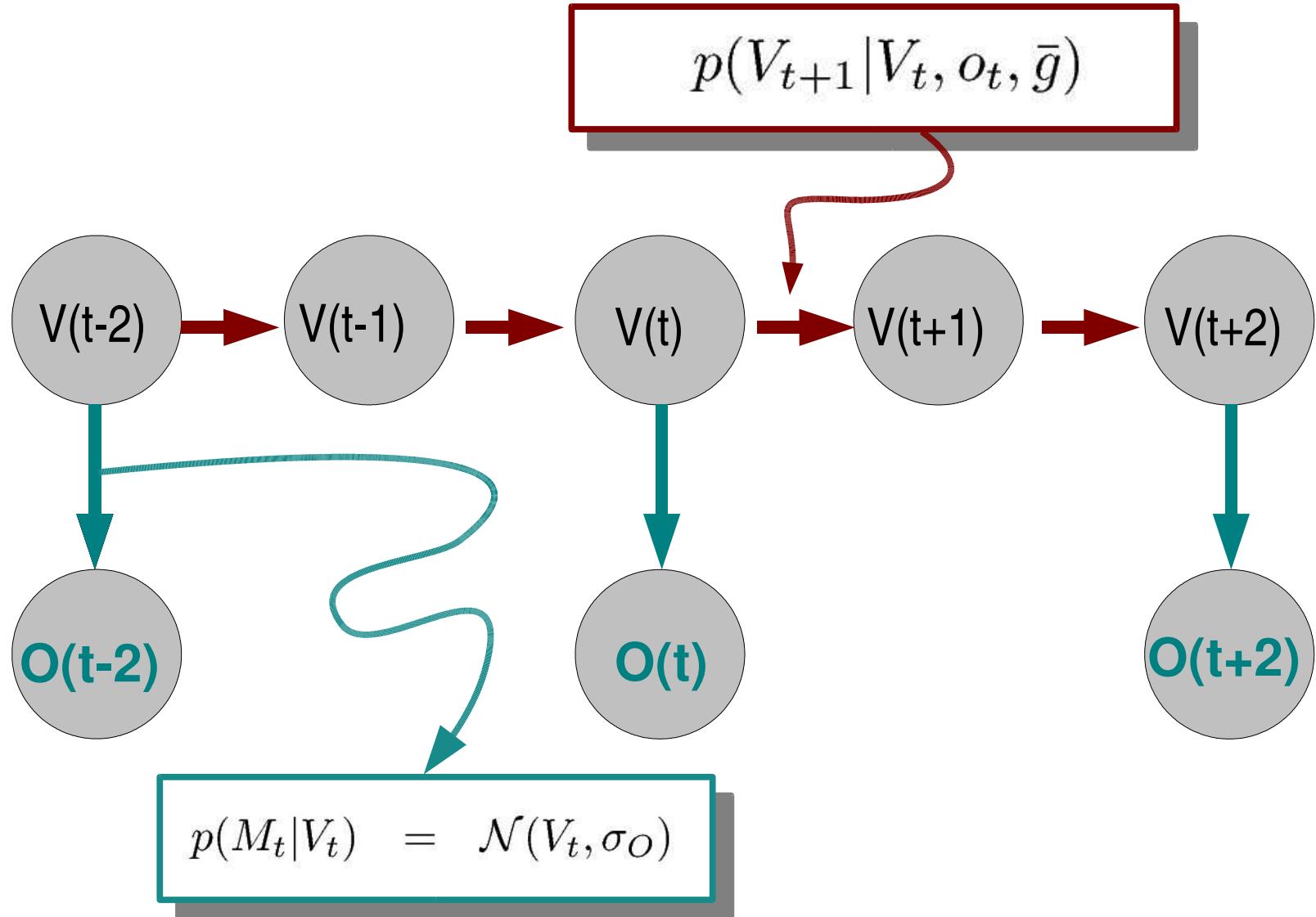
# Hidden dynamical system



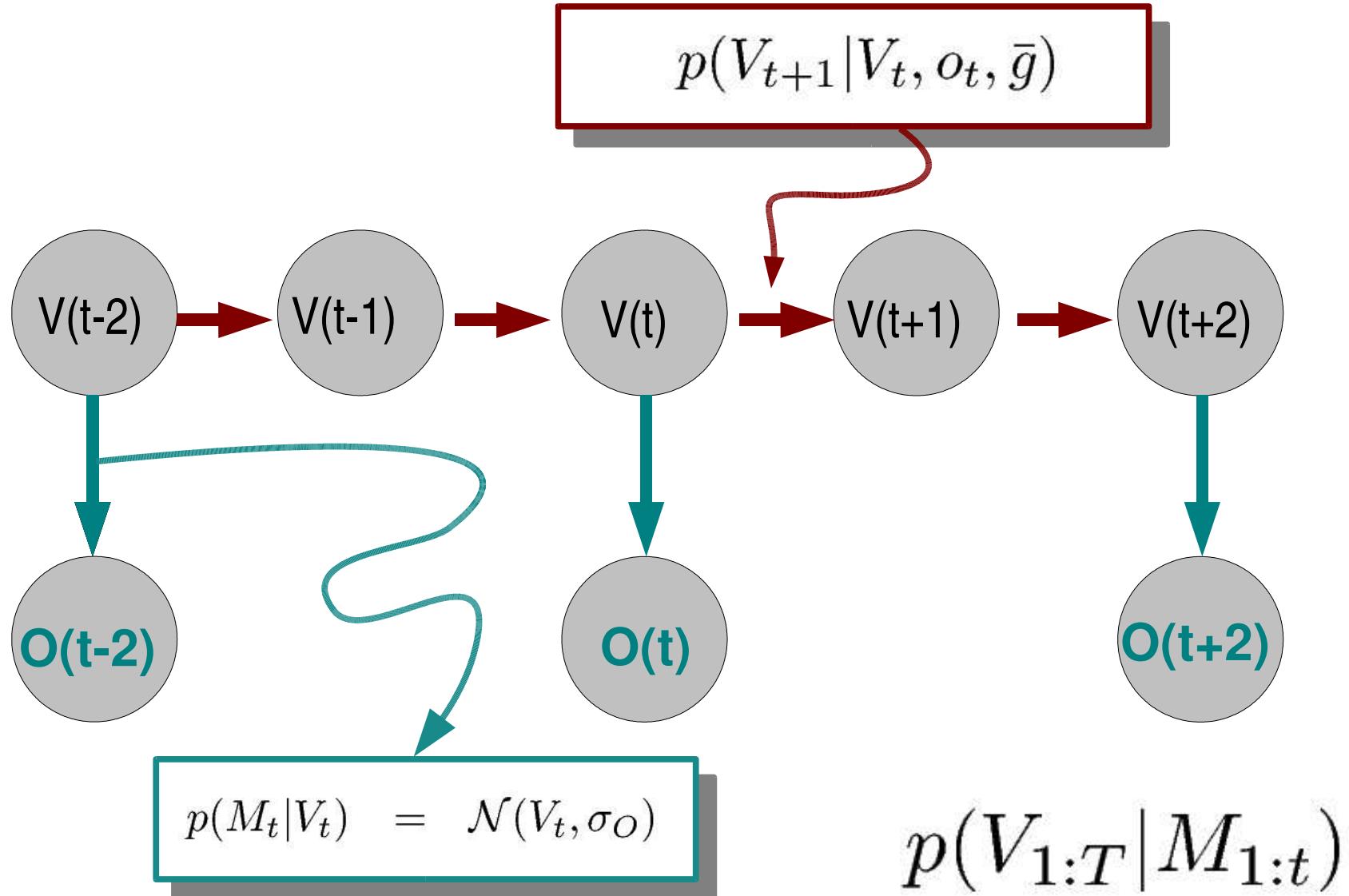
# Hidden dynamical system



# Hidden dynamical system



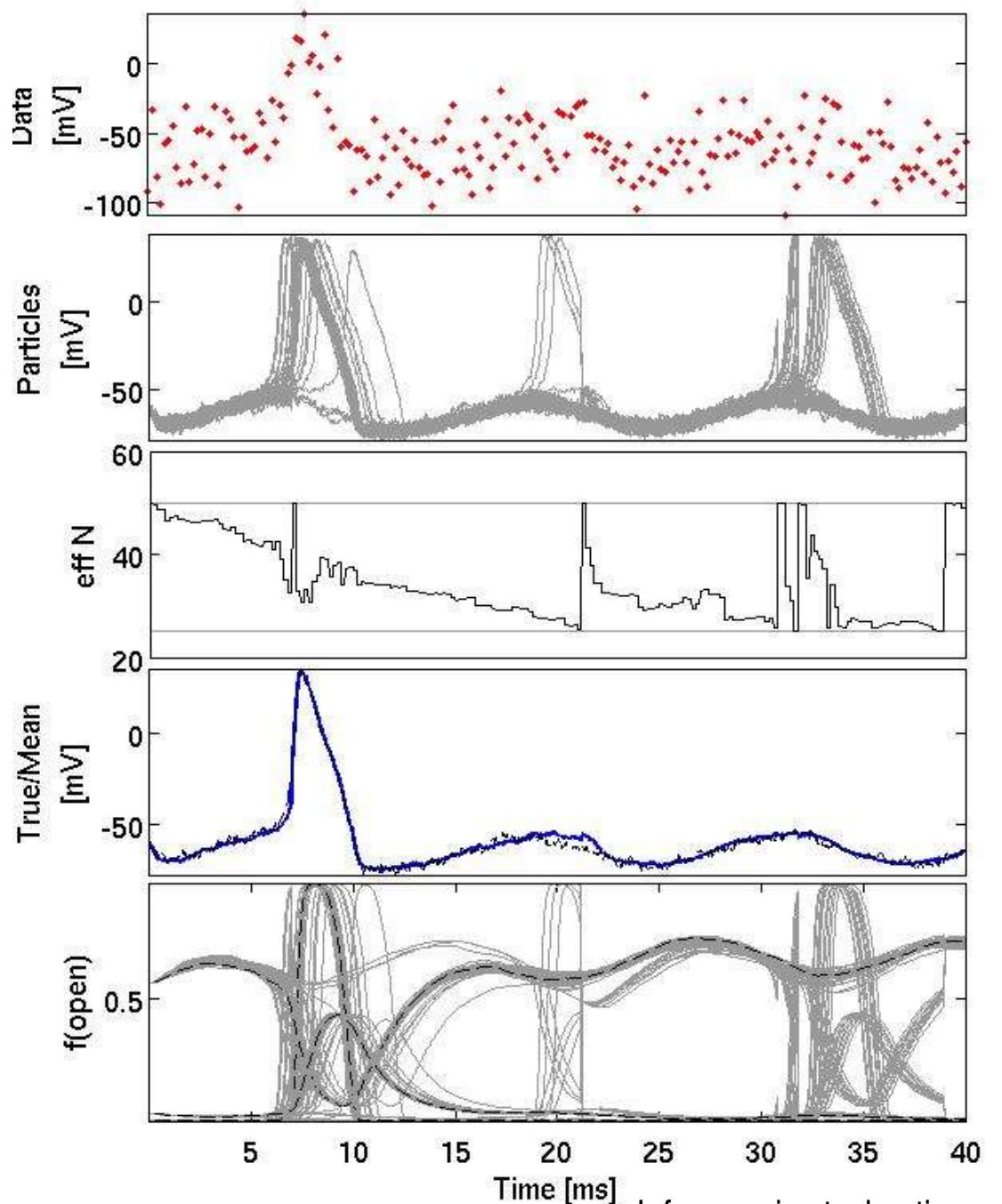
# Hidden dynamical system



# Model-based smoothing – know densities

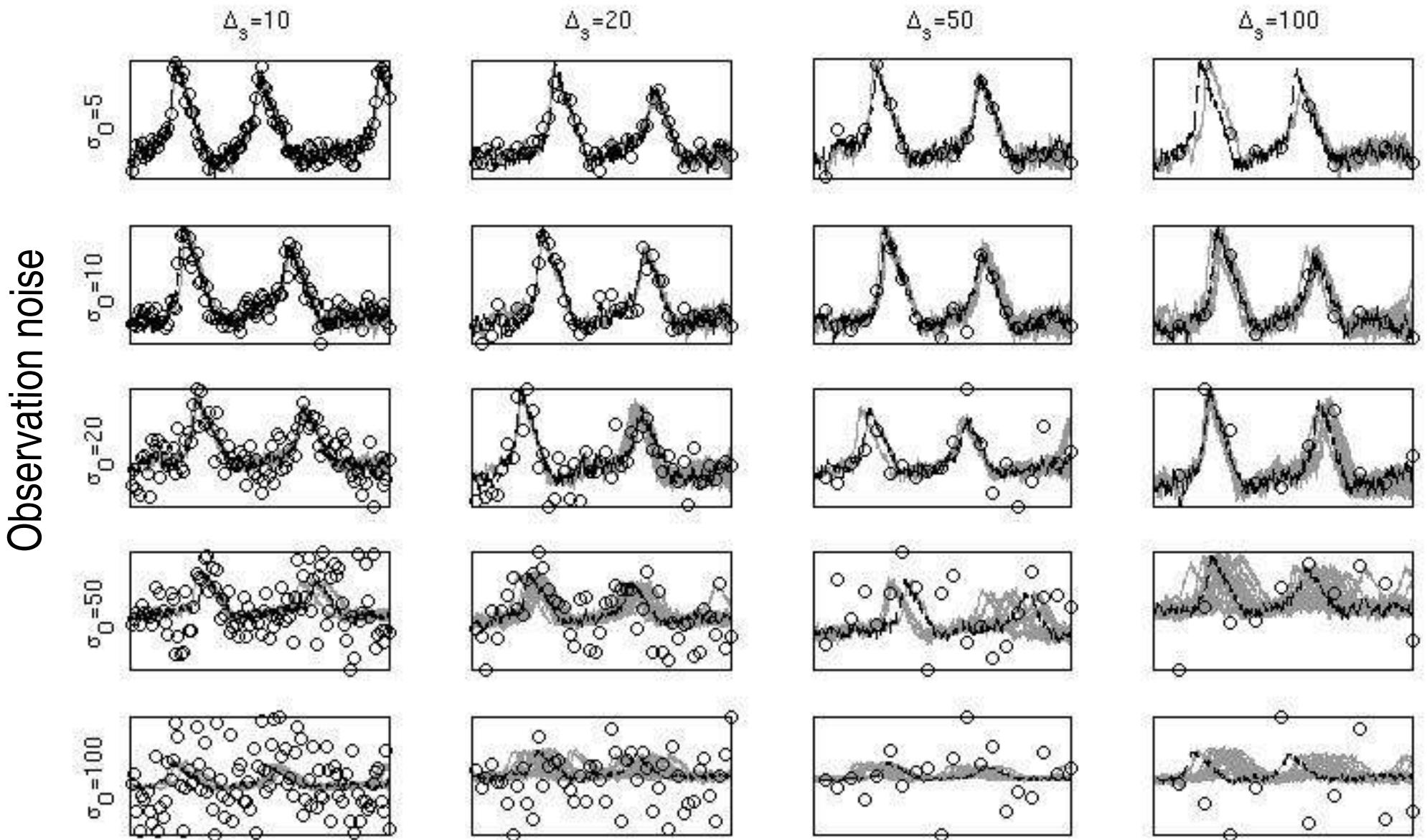
If true densities (and kinetics) are known, can do model-based smoothing.

Know lots, get lots.

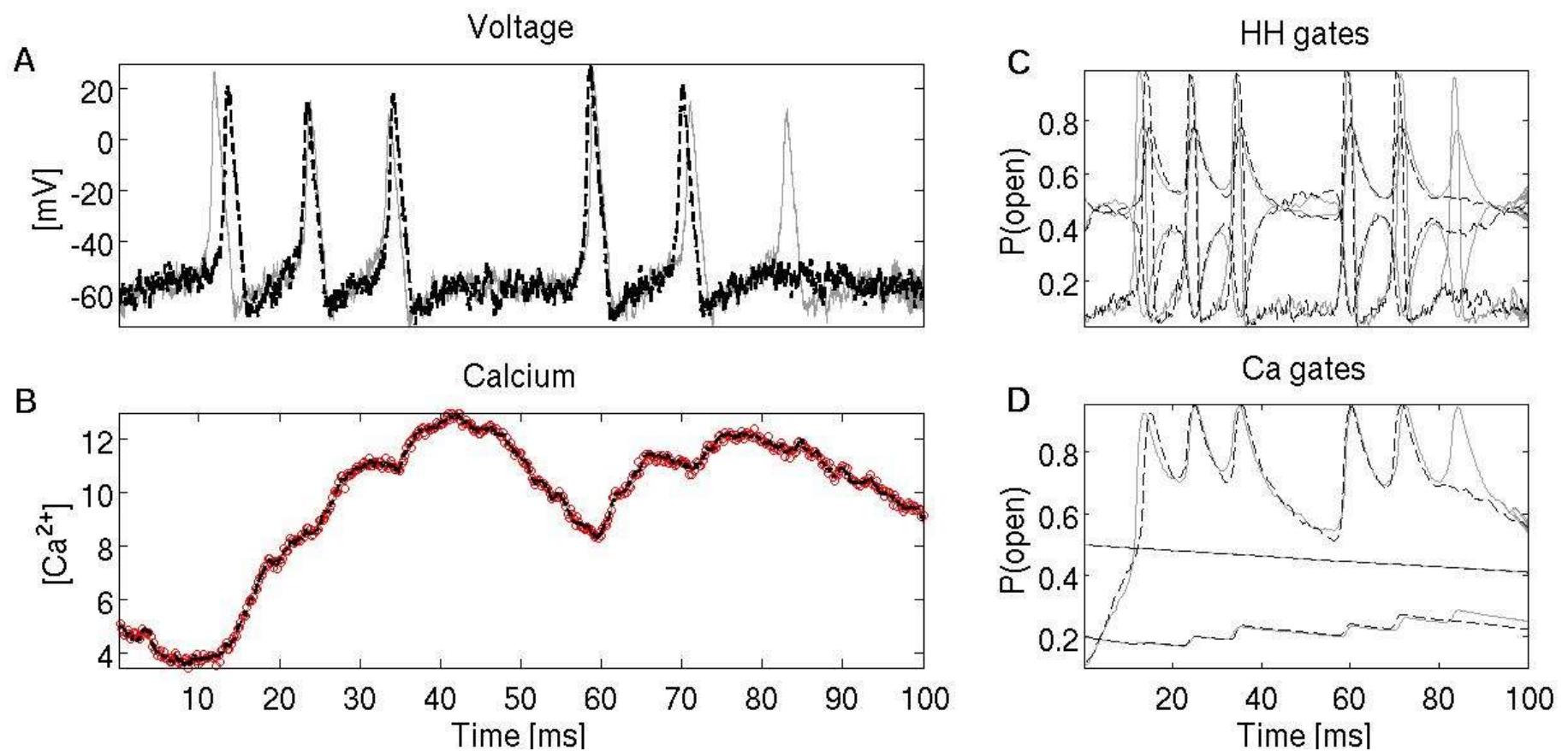


# Smoothing and upsampling

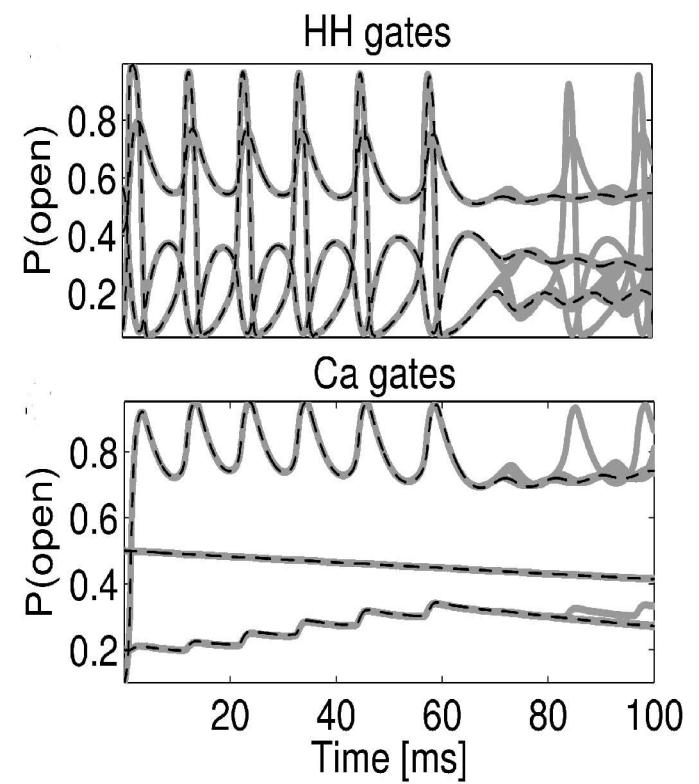
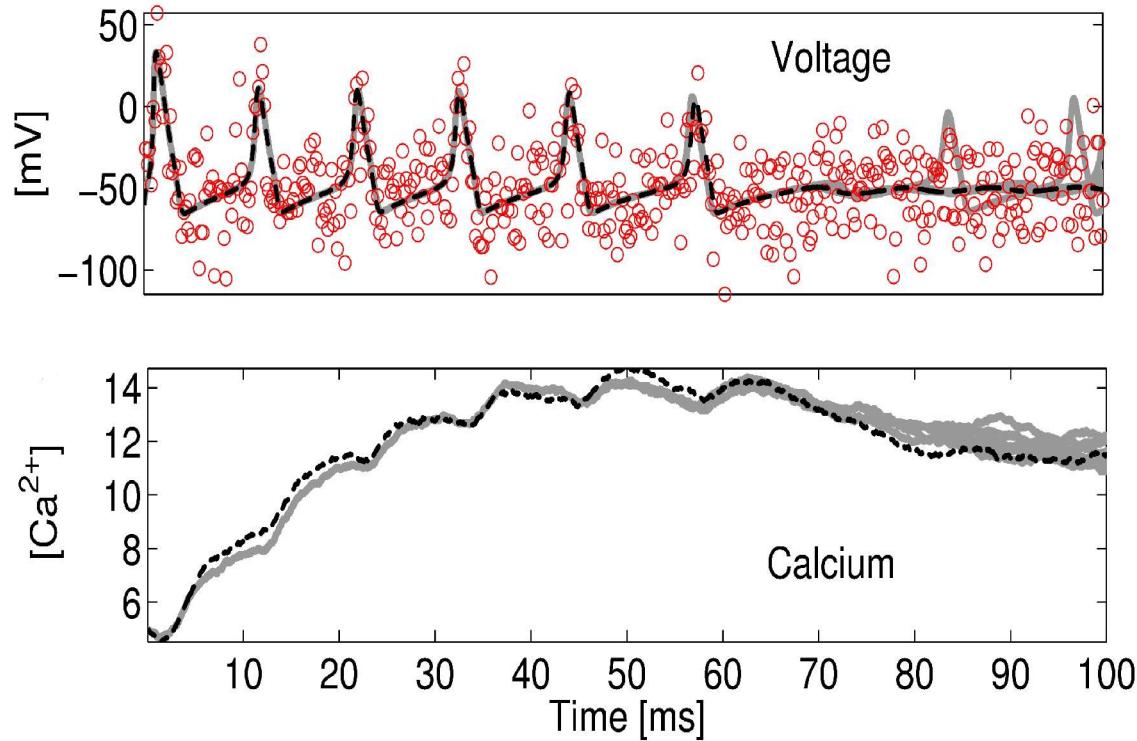
Temporal subsampling



# Voltage from [Ca]



# [Ca] from voltage



# EM for channel densities

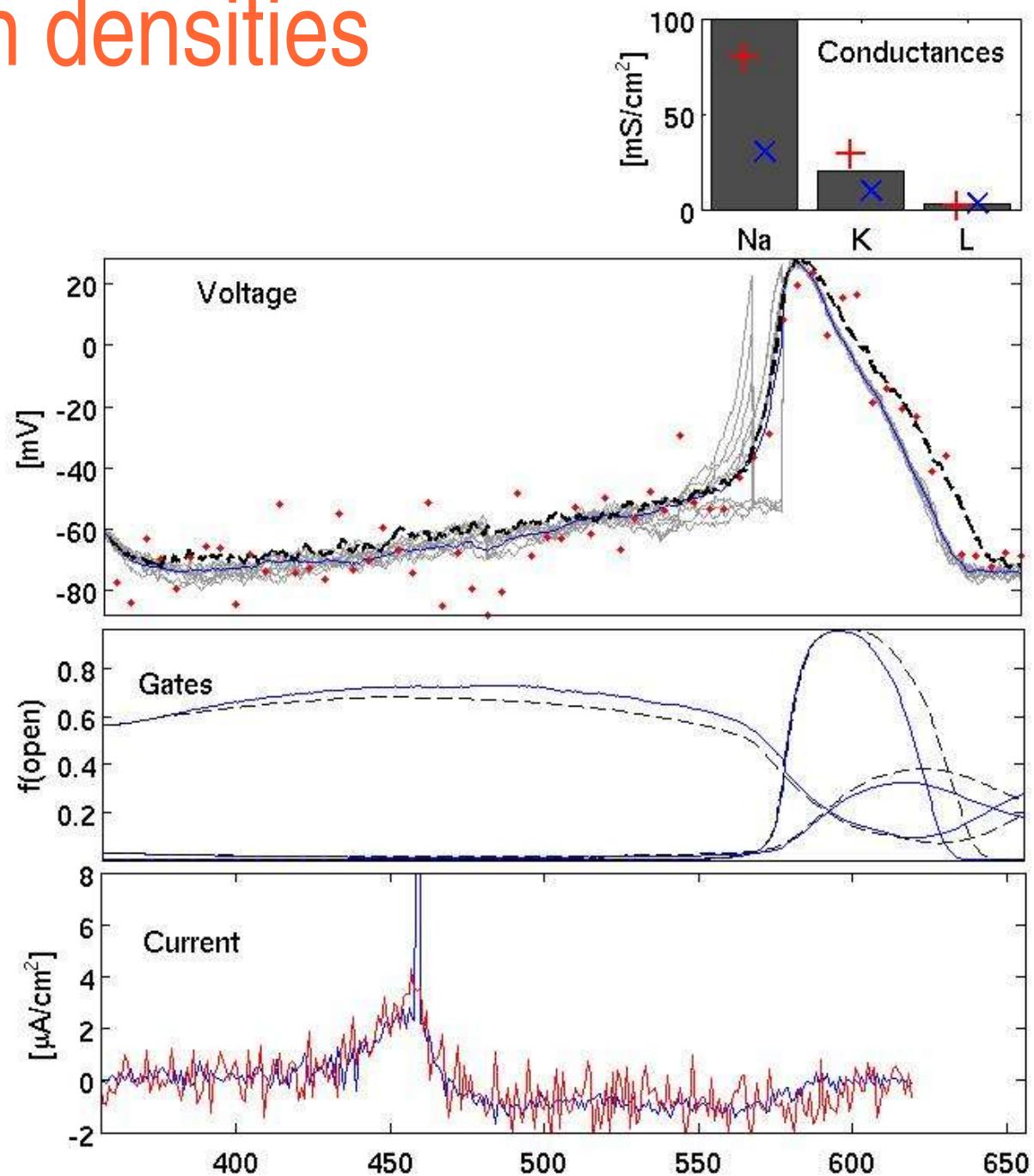
E step: infer some expected statistics given channel densities

$$\text{particle smoother: } w_t^i = \tilde{w}_t^i \left( \sum_j \frac{w_{t+1}^j p(V_{t+1}^j | V_t^i)}{\sum_k \tilde{w}_t^k p(V_{t+1}^j | V_t^k)} \right)$$

M step: update densities given expected sufficient statistics

$$\langle J_{ct} J_{c't} \rangle \quad \langle J_{ct} V_t \rangle \quad \langle J_{ct} V_{t+1} \rangle$$

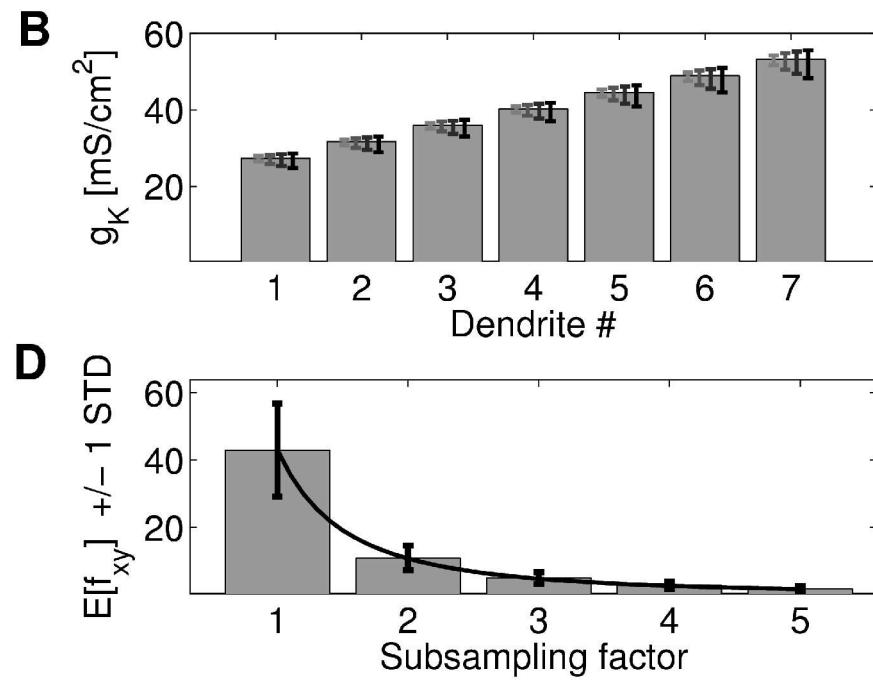
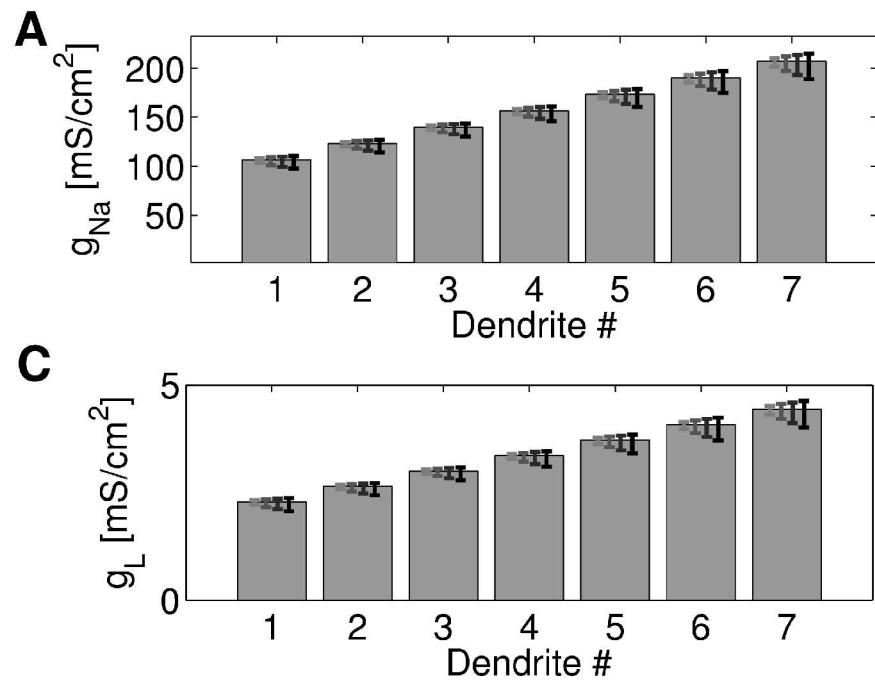
# EM: Unknown densities



# Discussion

- Assume known kinetics and noiseless observations
  - Channel density distributions in large compartmental models
  - Synaptic input time and strength
- Noisy observations
  - EM with particle smoothing
  - model-based smoothing (E)
  - parameter inference (M)
- BUT: still assume known kinetics

# Spatial subsampling



# E step: Particle smoothing

$$\begin{aligned}
 \langle V_{1:T} \rangle &= \int dV_{1:T} p(V_{1:T} | M_{1:t}) V_{1:T} \\
 &= \int dV_{1:T} q(V_{1:T}) \underbrace{\frac{p(V_{1:T} | M_{1:t})}{q(V_{1:T})}}_w V_{1:T}
 \end{aligned}$$

$V_{1:T}^i \sim q(V_{1:T})$	$\approx \sum_i V_{1:T}^i w_i$ (importance sampling)
-----------------------------	--

use exact distribution

$$\begin{aligned}
 q(V_t) &= p(V_t | V_{1:t-1}, M_{1:t}) \\
 &\propto p(V_t | V_{t-1}) p(V_{t-1} | V_{1:t-2}, M_{1:t-2})
 \end{aligned}$$

filter weights

$$w_t^{*i} = w_{t-1}^i p(M_t | V_t^i) \quad \tilde{w}_t^i = w_t^{*i} / (\sum_j w_t^{*j})$$

smoothing weights

$$w_t^i = \tilde{w}_t^i \left( \sum_j \frac{w_{t+1}^j p(V_{t+1}^j | V_t^i)}{\sum_k \tilde{w}_t^k p(V_{t+1}^j | V_t^k)} \right)$$

# Synaptic input

